

Using QTrobot

What is it?

[QTrobot](#) is described an expressive humanoid social robot.



What can it do?

Using its inbuilt functions and APIs you can get it do some interesting things. Have a look at its [competences page](#) to get a full understanding of its capabilities.

Powering on/off

Power on

To power on QTrobot, press down on the power button that is located behind the robot. You will see QT's head raise up and a face will be displayed on the screen that's on its head.



Power off

To power off QTrobot, simply press down on the power button. You should see the motors of the robot disengage and after a couple of minutes, the screen on QT's face will flash blue. After this, switch off the powersupply to the robot. This concludes the power off procedure.

How can I program it?

There are two ways of programming QTrobot.

1. [QTrobot Visual Studio](#)

2. [QTrobot Software Development Kit](#)

Everything you need to get started with programming the QTrobot can be found [here](#)

Additional Resources

1. LuxAI S.A. githubpage - [click here](#)
2. QTrobot questions and answers - [click here](#)

Revision #4

Created 2 February 2024 13:11:28 by Rohit Ramesh Thampy

Updated 24 October 2024 08:55:09 by Rohit Ramesh Thampy